

4.7 Brownian Bridge

黃于珊

4.7.1 Gaussian Process

Definition 4.7.1:

A Gaussian process $X(t)$, $t \geq 0$, is a stochastic process that has the property that, for arbitrary times $0 < t_1 < t_2 < \dots < t_n$, the random variables $X(t_1), X(t_2), \dots, X(t_n)$ are jointly normally distributed.

- The joint normal distribution of a set of vectors is determined by their means and covariances.

More generally, a random column vector $\mathbf{X} = (X_1, \dots, X_n)^{\text{tr}}$, where the superscript tr denotes transpose, is jointly normal if it has joint density

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{\sqrt{(2\pi)^n \det(C)}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}) C^{-1} (\mathbf{x} - \boldsymbol{\mu})^{\text{tr}} \right\}. \quad (2.2.18)$$

In equation (2.2.18), $\mathbf{x} = (x_1, \dots, x_n)$ is a row vector of dummy variables, $\boldsymbol{\mu} = (\mu_1, \dots, \mu_n)$ is the row vector of expectations, and C is the positive definite matrix of covariances.

- For a Gaussian process, the joint distribution of $X(t_1), X(t_2), \dots, X(t_n)$ is determined by the means and covariances of these random variables.
- We denote the mean of $X(t)$ by $m(t)$, and, for $s \geq 0, t \geq 0$, we denote the covariance of $X(s)$ and $X(t)$ by $c(s, t)$; i.e.,
$$m(t) = EX(t), c(s, t) = E[(X(s) - m(s))(X(t) - m(t))]$$

Example 4.7.2 (Brownian motion)

Brownian motion $W(t)$ is a Gaussian process.

For $0 < t_1 < t_2 < \dots < t_n$, the increments

$$I_1 = W(t_1), I_2 = W(t_2) - W(t_1), \dots, I_n = W(t_n) - W(t_{n-1})$$

$$\boxed{W(t_0) = 0}$$

are independent and normally distributed.

Increments over nonoverlapping time intervals are independent

$$W(t) - W(s) \sim N(0, t - s)$$

$$\boxed{W(t_2) = W(t_1) + I_2}$$

Writing

$$W(t_1) = I_1, W(t_2) = \sum_{j=1}^2 I_j, \dots, W(t_n) = \sum_{j=1}^n I_j,$$

Example 4.7.2 (Brownian motion)

$$0 < t_1 < t_2 < \dots < t_n$$

- The random variables $W(t_1), W(t_2), \dots, W(t_n)$ are jointly normally distributed. Gaussian process

Independent normal random variables are jointly normal.

 I_1, I_2, \dots, I_n are jointly normal

Linear combinations of jointly normal random variables are jointly normal.

- The mean function for Brownian motion is

$$m(t) = EW(t) = 0$$

Example 4.7.2 (Brownian motion)

- We may compute the covariance by letting $0 \leq s \leq t$ be given and noting that

$$\boxed{E[W(s)W(t)] - E[W(s)]E[W(t)]}$$


$$\begin{aligned} c(s, t) &= E[W(s)W(t)] = E[W(s)(W(t) - W(s) + W(s))] \\ &= E[W(s)(W(t) - W(s))] + E[W^2(s)] \end{aligned}$$

- Because $W(s)$ and $W(t) - W(s)$ are independent and both have mean zero, we see that

$$E[W(s)(W(t) - W(s))] = 0$$

Example 4.7.2 (Brownian motion)

$$\begin{aligned} c(s, t) &= E[W(s)W(t)] = E[W(s)(W(t) - W(s) + W(s))] \\ &= \cancel{E[W(s)(W(t) - W(s))]} + E[W^2(s)] \end{aligned}$$

- The other term, $E[W^2(s)]$, is the variance of $W(s)$, which is s .

$$\cancel{E[W^2(s)] - (E[W(s)])^2}$$

$$\text{Var}[W(t_{i+1}) - W(t_i)] = t_{i+1} - t_i. \quad (3.3.3)$$

Example 4.7.2 (Brownian motion)

- We conclude that $c(s,t)=s$ when $0 \leq s \leq t$.
- Reversing the roles of s and t , we conclude that $c(s,t)=t$ when $0 \leq t \leq s$.
- In general, the covariance function for Brownian motion is then

$$c(s,t) = s \wedge t,$$

where $s \wedge t$ denotes the minimum of s and t .

Example 4.7.3

(Itô integral of a deterministic integrand)

- Let $\Delta(t)$ be a nonrandom function of time, and define

$$I(t) = \int_0^t \Delta(s) dW(s)$$

where $W(t)$ is a Brownian motion. Then $I(t)$ is a Gaussian process, as we now show.

- In the proof of Theorem 4.4.9, we showed that, for fixed $u \in \mathbb{R}$, the process

$$M_u(t) = \exp\left\{uI(t) - \frac{1}{2}u^2 \int_0^t \Delta^2(s) ds\right\}$$

is a martingale.

Example 4.7.3

(Itô integral of a deterministic integrand)

$$M_u(t) = \exp\left\{uI(t) - \frac{1}{2}u^2 \int_0^t \Delta^2(s)ds\right\} \text{ is a martingale.}$$

• Then

$$1 = M_u(0) = EM_u(t) = e^{-\frac{1}{2}u^2 \int_0^t \Delta^2(s)ds} \cdot Ee^{uI(t)}$$

and we thus obtained the moment-generating function formula

$$Ee^{uI(t)} = e^{\frac{1}{2}u^2 \int_0^t \Delta^2(s)ds}$$

$$\begin{aligned} X &\sim \mathcal{N}(\mu, \sigma^2) \\ M_X(t) &= \mathbb{E}(e^{tX}) \\ &= e^{t\mu + t^2\sigma^2/2} \end{aligned}$$

(with mean zero and variance $\int_0^t \Delta^2(s)ds$)

• $I(t) \sim \mathcal{N}(0, \int_0^t \Delta^2(s)ds)$

Example 4.7.3

(Itô integral of a deterministic integrand)

- We have shown that $I(t)$ is normally distributed, verification that the process is Gaussian requires more.
- Verify that, for $0 < t_1 < t_2 < \dots < t_n$, the random variables $I(t_1), I(t_2), \dots, I(t_n)$ are jointly normally distributed.

Example 4.7.3

(Itô integral of a deterministic integrand)

- It turns out that the increments $I(t) \sim N(0, \int_0^t \Delta^2(s) ds)$
 $I(t_1) - I(0), I(t_2) - I(t_1), \dots, I(t_n) - I(t_{n-1})$
are **normally distributed** and **independent**(p.14),
and from this the joint normality of $I(t_1), I(t_2), \dots, I(t_n)$
follows by the same argument as used in Example
4.7.2 for Brownian motion.

$$I(t_1) = (I(t_1) - I(0))$$

$$I(t_2) = (I(t_2) - I(t_1)) + (I(t_1) - I(0))$$

Independent normal random variables are jointly normal.

➡ $(I(t_1) - I(0)), (I(t_2) - I(t_1)), \dots, (I(t_n) - I(t_{n-1}))$ are jointly normal

Linear combinations of jointly normal random variables are jointly normal.

Example 4.7.3

(Itô integral of a deterministic integrand)

- Next, we show that, for $0 < t_1 < t_2$, the two random increments $I(t_1) - I(0) = I(t_1)$ and $I(t_2) - I(t_1)$ are normally distributed and independent.
- The argument we provide can be iterated to prove this result for any number of increments.

Example 4.7.3

(Itô integral of a deterministic integrand)

- For fixed $u_2 \in R$, the martingale property of M_{u_2} implies that

$$M_{u_2}(t_1) = E[M_{u_2}(t_2) | F(t_1)]$$

- Now let $u_1 \in R$ be fixed. Because $\frac{M_{u_1}(t_1)}{M_{u_2}(t_1)}$ is $F(t_1)$ -measurable, we may multiply the equation above by this quotient to obtain

$$M_{u_1}(t_1) = E \left[\frac{M_{u_1}(t_1)M_{u_2}(t_2)}{M_{u_2}(t_1)} \mid F(t_1) \right] \boxed{M_u(t) = \exp \left\{ uI(t) - \frac{1}{2} u^2 \int_0^t \Delta^2(s) ds \right\}}$$

$$= E \left[\exp \left\{ u_1 I(t_1) + u_2 (I(t_2) - I(t_1)) - \frac{1}{2} u_1^2 \int_0^{t_1} \Delta^2(s) ds - \frac{1}{2} u_2^2 \int_{t_1}^{t_2} \Delta^2(s) ds \right\} \mid F(t_1) \right]$$

Example 4.7.3

(Itô integral of a deterministic integrand)

$$M_{u_1}(t_1) = E \left[\exp \left\{ u_1 I(t_1) + u_2 (I(t_2) - I(t_1)) - \frac{1}{2} u_1^2 \int_0^{t_1} \Delta^2(s) ds - \frac{1}{2} u_2^2 \int_{t_1}^{t_2} \Delta^2(s) ds \right\} \mid F(t_1) \right]$$

- We now take expectations

$$1 = M_{u_1}(0) = EM_{u_1}(t_1)$$

$$M_u(t) = \exp \left\{ uI(t) - \frac{1}{2} u^2 \int_0^t \Delta^2(s) ds \right\}$$

$$\begin{aligned} \mathbb{E}(\mathbb{E}[X|\mathcal{G}]) \\ = \mathbb{E}X \end{aligned}$$

$$\begin{aligned} &= E \left[\exp \left\{ u_1 I(t_1) + u_2 (I(t_2) - I(t_1)) - \frac{1}{2} u_1^2 \int_0^{t_1} \Delta^2(s) ds - \frac{1}{2} u_2^2 \int_{t_1}^{t_2} \Delta^2(s) ds \right\} \right] \\ &= E \left[\exp \{ u_1 I(t_1) + u_2 (I(t_2) - I(t_1)) \} \right] \cdot \exp \left\{ -\frac{1}{2} u_1^2 \int_0^{t_1} \Delta^2(s) ds - \frac{1}{2} u_2^2 \int_{t_1}^{t_2} \Delta^2(s) ds \right\} \end{aligned}$$

- Where we have used the fact that $\Delta^2(s)$ is nonrandom to take the integrals of $\Delta^2(s)$ outside the expectation on the right-hand side.¹⁶

Example 4.7.3

(Itô integral of a deterministic integrand)

$$1 = E[\exp\{u_1 I(t_1) + u_2 (I(t_2) - I(t_1))\}] \cdot \exp\left\{-\frac{1}{2} u_1^2 \int_0^{t_1} \Delta^2(s) ds - \frac{1}{2} u_2^2 \int_{t_1}^{t_2} \Delta^2(s) ds\right\}$$

- This leads to the moment-generating function formula

$$\begin{aligned} & E[\exp\{u_1 I(t_1) + u_2 (I(t_2) - I(t_1))\}] \\ &= \exp\left\{\frac{1}{2} u_1^2 \int_0^{t_1} \Delta^2(s) ds\right\} \cdot \exp\left\{\frac{1}{2} u_2^2 \int_{t_1}^{t_2} \Delta^2(s) ds\right\} \end{aligned}$$

Example 4.7.3

(Itô integral of a deterministic integrand)

$$\begin{aligned} & E\left[\exp\{u_1 I(t_1) + u_2 (I(t_2) - I(t_1))\}\right] \\ &= \exp\left\{\frac{1}{2} u_1^2 \int_0^{t_1} \Delta^2(s) ds\right\} \cdot \exp\left\{\frac{1}{2} u_2^2 \int_{t_1}^{t_2} \Delta^2(s) ds\right\} \end{aligned}$$

- The right hand side is the product of
 - the moment-generating function for a normal random variable with mean zero and variance $\int_0^{t_1} \Delta^2(s) ds$
 - the moment-generating function for a normal random variable with mean zero and variance $\int_{t_1}^{t_2} \Delta^2(s) ds$

$$\begin{aligned} X &\sim \mathcal{N}(\mu, \sigma^2) \\ M_X(t) &= \mathbb{E}(e^{tX}) \\ &= e^{t\mu + t^2\sigma^2/2} \end{aligned}$$

Example 4.7.3

(Itô integral of a deterministic integrand)

$$E[\exp\{u_1 I(t_1) + u_2 (I(t_2) - I(t_1))\}] \quad I(t) \sim N(0, \int_0^t \Delta^2(s) ds)$$
$$= \exp\left\{\frac{1}{2} u_1^2 \int_0^{t_1} \Delta^2(s) ds\right\} \cdot \exp\left\{\frac{1}{2} u_2^2 \int_{t_1}^{t_2} \Delta^2(s) ds\right\}$$

$$I(t_1) \sim N(0, \int_0^{t_1} \Delta^2(s) ds) \quad I(t_2) - I(t_1) \sim N(0, \int_{t_1}^{t_2} \Delta^2(s) ds)$$

- It follows that $I(t_1)$ and $I(t_2) - I(t_1)$ must have these distributions, and because their joint moment-generating function factors into this **product of moment-generating functions**, they must be independent.

Example 4.7.3

(Itô integral of a deterministic integrand)

$$E[I(t_1)I(t_2)] - E[I(t_1)]E[I(t_2)]$$

- We have $c(t_1, t_2) = E[I(t_1)I(t_2)] = E[I(t_1)(I(t_2) - I(t_1) + I(t_1))]$
 $= E[I(t_1)(I(t_2) - I(t_1))] + EI^2(t_1)$

$$EI^2(t) = \int_0^t \Delta^2(s) ds$$

$I(t_1)$ 和 $I(t_2)-I(t_1)$ 獨立

$$= EI(t_1) \cdot E[I(t_2) - I(t_1)] + \int_0^{t_1} \Delta^2(s) ds$$

$$= \int_0^{t_1} \Delta^2(s) ds \quad 0 < t_1 < t_2$$

- For the general case where $s \geq 0$ and $t \geq 0$ and we do not know the relationship between s and t , we have the covariance formula

$$c(s, t) = \int_0^{s \wedge t} \Delta^2(u) du$$

4.7.2 Brownian Bridge as a Gaussian Process

Definition 4.7.4.

Let $W(t)$ be a Brownian motion. Fix $T > 0$. We define the Brownian bridge from 0 to 0 (p.22) on $[0, T]$ to be the process

$$X(t) = W(t) - \frac{t}{T}W(T), 0 \leq t \leq T \quad (4.7.2)$$

4.7.2 Brownian Bridge as a Gaussian Process

$$X(t) = W(t) - \frac{t}{T}W(T), 0 \leq t \leq T$$

- The process $X(t)$ satisfies

$$X(0) = X(T) = 0$$

t=0	$X(0) = W(0) - 0 = 0$
t=T	$X(T) = W(T) - W(T) = 0$

- Because $W(T)$ enters the definition of $X(t)$ for $0 \leq t \leq T$, the Brownian bridge $X(t)$ is not adapted to the filtration $F(t)$ generated by $W(t)$.

4.7.2 Brownian Bridge as a Gaussian Process

$$X(t) = W(t) - \frac{t}{T}W(T), 0 \leq t \leq T$$

- For $0 < t_1 < t_2 < \dots < t_n < T$, the random variables

$$X(t_1) = W(t_1) - \frac{t_1}{T}W(T), \dots, X(t_n) = W(t_n) - \frac{t_n}{T}W(T)$$

are jointly normal because $W(t_1), \dots, W(t_n), W(T)$ are jointly normal.

p.6 Example 4.7.2

Linear combinations of jointly normal random variables are jointly normal.

- Hence, the Brownian bridge from 0 to 0 is a Gaussian process.

4.7.2 Brownian Bridge as a Gaussian Process

- Its mean function is easily seen to be

$$X(t) = W(t) - \frac{t}{T}W(T)$$

$$m(t) = EX(t) = E\left[W(t) - \frac{t}{T}W(T)\right] = 0$$

- For $s, t \in (0, T)$, we compute the covariance

function $E[X(s)X(t)] - E[X(s)]E[X(t)]$

$$c(s, t) = E\left[\left(W(s) - \frac{s}{T}W(T)\right)\left(W(t) - \frac{t}{T}W(T)\right)\right] - E[W(s)W(t)] = s \wedge t$$

$$= E[W(s)W(t)] - \frac{t}{T}E[W(s)W(T)] - \frac{s}{T}E[W(t)W(T)] + \frac{st}{T^2}EW^2(T)$$

$$= s \wedge t - \frac{2st}{T} + \frac{st}{T} = s \wedge t - \frac{st}{T}$$

4.7.2 Brownian Bridge as a Gaussian Process

Definition 4.7.5.

Let $W(t)$ be a Brownian motion. Fix $T > 0$, $a \in \mathbb{R}$ and $b \in \mathbb{R}$. We define the Brownian bridge from a to b on $[0, T]$ to be the process

$$\underbrace{X^{a \rightarrow b}}_{\text{Gaussian process}}(t) = a + \frac{(b-a)t}{T} + \underbrace{X(t)}_{\text{Gaussian process}}, 0 \leq t \leq T$$

where $X(t) = X^{0 \rightarrow 0}$ is the Brownian bridge from 0 to 0. Begins at a at time 0 and ends at b at time T .

$$t=0 \quad X^{a \rightarrow b}(0) = a + 0 + X(0) = a$$

$$t=T \quad X^{a \rightarrow b}(T) = a + (b-a) + X(T) = b$$

$$\boxed{X(0) = X(T) = 0}$$

Adding a nonrandom function to a Gaussian process gives us another Gaussian process.

4.7.2 Brownian Bridge as a Gaussian Process

- The mean function is affected: $X^{a \rightarrow b}(t) = a + \frac{(b-a)t}{T} + X(t)$

$$m^{a \rightarrow b}(t) = EX^{a \rightarrow b}(t) = a + \frac{(b-a)t}{T} \quad EX(t) = 0$$

- However, the covariance function is not affected:

$$c^{a \rightarrow b}(s, t) = E\left[\left(X^{a \rightarrow b}(s) - m^{a \rightarrow b}(s)\right)\left(X^{a \rightarrow b}(t) - m^{a \rightarrow b}(t)\right)\right] = s \wedge t - \frac{st}{T}$$

$$\begin{aligned} &= E\left[\left(\left(a + \frac{(b-a)s}{T} + X(s)\right) - \left(a + \frac{(b-a)s}{T}\right)\right)\left(\left(a + \frac{(b-a)t}{T} + X(t)\right) - \left(a + \frac{(b-a)t}{T}\right)\right)\right] \\ &= E[X(s)X(t)] \quad E[X(s)X(t)] = s \wedge t - \frac{st}{T} \end{aligned}$$

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- We cannot write the Brownian bridge as a stochastic integral of a deterministic integrand because the variance of the Brownian bridge,

$$EX(t) = 0 \quad EX^2(t) = c(t,t) = t - \frac{t^2}{T} = \frac{t(T-t)}{T} \quad \begin{matrix} X(s) X(t) \\ c(s,t) = s \wedge t - \frac{st}{T} \end{matrix}$$

increases for $0 \leq t \leq T/2$ and then decreases for $T/2 \leq t \leq T$.

- In Example 4.7.3, the variance of $I(t) = \int_0^t \Delta(u) dW(u)$ is $\int_0^t \Delta^2(u) du$, which is nondecreasing in t .

$$\begin{aligned} \text{F.O.C } 1 - \frac{2t}{T} &= 0 \\ t &= \frac{T}{2} \\ \text{S.O.C } -\frac{2}{T} &< 0 \end{aligned}$$

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- We can obtain a process with the same distribution as the Brownian bridge from 0 to 0 as a scaled stochastic integral.

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- Consider

$$Y(t) = (T - t) \int_0^t \frac{1}{T - u} dW(u), 0 \leq t < T$$

p.31

- The integral $I(t) = \int_0^t \frac{1}{T - u} dW(u)$

is a Gaussian process of the type discussed in Example 4.7.3, provided $t < T$ so the integrand is defined.

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- For $0 < t_1 < t_2 < \dots < t_n < T$, the random variables

$$Y(t_1) = (T - t_1)I(t_1), Y(t_2) = (T - t_2)I(t_2), \dots, Y(t_n) = (T - t_n)I(t_n)$$

are jointly normal because $I(t_1), I(t_2), \dots, I(t_n)$ are jointly normal.

- In particular, Y is a Gaussian process.

$$Y(t) = (T - t) \int_0^t \frac{1}{T - u} dW(u), 0 \leq t < T \quad I(t) = \int_0^t \frac{1}{T - u} dW(u)$$

Linear combinations of jointly normal random variables are jointly normal.

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- The mean and covariance functions of I are

$$m^I(t) = 0$$

$\left[\frac{1}{T-u}\right]_0^{s \wedge t}$	$V=T-u$	$\int -V^{-2}dV$
	$dV=-du$	$[V^{-1}]$

$$c^I(s, t) = \int_0^{s \wedge t} \frac{1}{(T-u)^2} du = \frac{1}{T-s \wedge t} - \frac{1}{T} \text{ for all } s, t \in [0, T)$$

- This means that the mean function for Y is

$$m^Y(t) = 0$$

$$I(t) \sim N(0, \int_0^t \Delta^2(s) ds) \quad c(s, t) = \int_0^{s \wedge t} \Delta^2(u) du$$

$$I(t) = \int_0^t \frac{1}{T-u} dW(u) \quad Y(t) = (T-t) \int_0^t \frac{1}{T-u} dW(u)$$

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- To compute the covariance function for Y , we assume for the moment that $0 \leq s \leq t \leq T$ so that

$$c^I(s, t) = \frac{1}{T-s} - \frac{1}{T} = \frac{s}{T(T-s)}$$

$$c^I(s, t) = \frac{1}{T-s \wedge t} - \frac{1}{T}$$

Then

$$E[Y(s)Y(t)] - E[Y(s)]E[Y(t)]$$

$$c^Y(s, t) = E[(T-s)(T-t)I(s)I(t)] = (T-s)(T-t) \frac{s}{T(T-s)} = \frac{(T-t)s}{T} = s - \frac{st}{T}$$

- If we had taken $0 \leq t \leq s < T$, the roles of s and t would have been reversed. In general

$$c^Y(s, t) = s \wedge t - \frac{st}{T}, \forall s, t \in [0, T)$$

$$Y(t) = (T-t) \int_0^t \frac{1}{T-u} dW(u)$$

$$I(t) = \int_0^t \frac{1}{T-u} dW(u)$$

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- This is the same covariance formula (4.7.3) we obtained for the Brownian bridge.
- Because the mean and covariance functions for Gaussian process completely determine the distribution of the process, we conclude that the process Y has the same distribution as the Brownian bridge from 0 to 0 on $[0, T]$.

$m(t) = EX(t) = 0$	$m^Y(t) = 0$
$c(s, t) = s \wedge t - \frac{st}{T}$	$c^Y(s, t) = s \wedge t - \frac{st}{T}$

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- We now consider the variance

$$\boxed{m^Y(t) = 0} \quad EY^2(t) = c^Y(t, t) = \frac{t(T-t)}{T}, 0 < t < T \quad \boxed{c^Y(s, t) = s \wedge t - \frac{st}{T}}$$

- Note that, as $t \rightarrow T$, this variance converges to 0.
 - As $t \rightarrow T \Rightarrow$ the random process $Y(t)$ has mean=0
 \Rightarrow variance converges to 0.
- We did not initially define $Y(T)$, but this observation suggests that it makes sense to define $Y(T)=0$.
- If we do that, then $Y(t)$ is continuous at $t=T$.

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

Theorem 4.7.6

Define the process

$$Y(t) = \begin{cases} (T-t) \int_0^t \frac{1}{T-u} dW(u) & \text{for } 0 \leq t < T, \\ 0 & \text{for } t = T \end{cases}$$

Then $Y(t)$ is a continuous Gaussian process on $[0, T]$ and has mean and covariance functions

$$m^Y(t) = 0, t \in [0, T]$$

$$c^Y(s, t) = s \wedge t - \frac{st}{T}, \forall s, t \in [0, T]$$

In particular, the process $Y(t)$ has the same distribution as the Brownian bridge from 0 to 0 on $[0, T]$ (Definition 4.7.5)

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- We note that the process $Y(t)$ is adapted to the filtration generated by the Brownian motion $W(t)$.

$$Y(t) = (T - t) \int_0^t \frac{1}{T - u} dW(u).$$

- Compute the stochastic differential of $Y(t)$, which is

$$Y(t) = (T - t) \int_0^t \frac{1}{T - u} dW(u)$$

$$dY(t) = \int_0^t \frac{1}{T - u} dW(u) \cdot d(T - t) + (T - t) \cdot d \int_0^t \frac{1}{T - u} dW(u)$$

$$= - \int_0^t \frac{1}{T - u} dW(u) \cdot dt + dW(t)$$

$$= - \frac{Y(t)}{T - t} dt + dW(t)$$

$$I(t) = \int_0^t \Delta(u) dW(u) \quad (4.2.11)$$

$$dI(t) = \Delta(t) dW(t) \quad (4.2.12)$$

$$I(t) = \int_0^t \frac{1}{T - u} dW(u)$$

$$\frac{1}{T - t} dW(t)$$

4.7.3 Brownian Bridge as a Scaled Stochastic Integral

- If $Y(t)$ is positive as t approaches T , the drift term $-\frac{Y(t)}{T-t}dt$ becomes large in absolute value and is negative.
 - This drives $Y(t)$ toward zero.
- On the other hand, if $Y(t)$ is negative, the drift term becomes large and positive, and this again drives $Y(t)$ toward zero.
- This strongly suggests, and it is indeed true, that as $t \rightarrow T$ the process $Y(t)$ converges to zero almost surely.

$$dY(t) = -\frac{Y(t)}{T-t}dt + dW(t)$$

4.7.4 Multidimensional Distribution of the Brownian Bridge

- We fix $a \in \mathbb{R}$ and $b \in \mathbb{R}$ and let $X^{a \rightarrow b}(t)$ denote the Brownian bridge from a to b on $[0, T]$. We also fix $0 = t_0 < t_1 < t_2 < \dots < t_n < T$. In this section, We compute the joint density of $X^{a \rightarrow b}(t_1), \dots, X^{a \rightarrow b}(t_n)$. We recall that the Brownian bridge from a to b has the mean function

$$m^{a \rightarrow b}(t) = a + \frac{(b-a)t}{T} = \frac{(T-t)a}{T} + \frac{bt}{T}$$

and covariance function

$$c(s, t) = s \wedge t - \frac{st}{T}$$

When $s \leq t$, we may write this as

$$c(s, t) = s - \frac{st}{T} = \frac{s(T-t)}{T}, \quad 0 \leq s \leq t \leq T$$

To simplify notation, we set $\tau_j = T - t_j$ so that $\tau_0 = T$. $T - t_0$

- We define random variable

$$Z_j = \frac{X^{a \rightarrow b}(t_j)}{\tau_j} - \frac{X^{a \rightarrow b}(t_{j-1})}{\tau_{j-1}}$$

Because $X^{a \rightarrow b}(t_1), \dots, X^{a \rightarrow b}(t_n)$ are jointly normal, so that $Z(t_1), \dots, Z(t_n)$ are jointly normal. We compute EZ_j , $Var(Z_j)$ and $Cov(Z_i, Z_j)$.

Linear combinations of jointly normal random variables are jointly normal.

$$\begin{aligned}
 E(Z_j) &= \frac{1}{\tau_j} EX^{a \rightarrow b}(t_j) - \frac{1}{\tau_{j-1}} EX^{a \rightarrow b}(t_{j-1}) = \frac{\cancel{a}}{T} + \frac{bt_j}{T\tau_j} - \frac{\cancel{a}}{T} - \frac{bt_{j-1}}{T\tau_{j-1}} = \frac{bt_j(T - \cancel{t_{j-1}}) - bt_{j-1}(T - \cancel{t_j})}{T\tau_j\tau_{j-1}} \\
 &= \frac{b(t_j - t_{j-1})}{\tau_j\tau_{j-1}}.
 \end{aligned}$$

$\tau_j = T - t_j$

$$\begin{aligned}
 &\frac{(T - t_j)a}{T} + \frac{bt_j}{T} \quad \frac{(T - t_{j-1})a}{T} + \frac{bt_{j-1}}{T}
 \end{aligned}$$

$$Z_j = \frac{X^{a \rightarrow b}(t_j)}{\tau_j} - \frac{X^{a \rightarrow b}(t_{j-1})}{\tau_{j-1}}$$

$$m^{a \rightarrow b}(t) = a + \frac{(b-a)t}{T} = \frac{(T-t)a}{T} + \frac{bt}{T}$$

$$\begin{aligned}
\text{Var}(Z_j) &= \frac{1}{\tau_j^2} \text{Var}(X^{a \rightarrow b}(t_j)) - \frac{2}{\tau_j \tau_{j-1}} \text{Cov}(X^{a \rightarrow b}(t_j), X^{a \rightarrow b}(t_{j-1})) + \frac{1}{\tau_{j-1}^2} \text{Var}(X^{a \rightarrow b}(t_{j-1})) \\
&= \frac{1}{\tau_j^2} c(t_j, t_j) - \frac{2}{\tau_j \tau_{j-1}} c(t_j, t_{j-1}) + \frac{1}{\tau_{j-1}^2} c(t_{j-1}, t_{j-1}) \\
&= \frac{t_j}{T \tau_j} - \frac{2t_{j-1}}{T \tau_{j-1}} + \frac{t_{j-1}}{T \tau_{j-1}} = \frac{t_j(T - t_{j-1}) - 2t_{j-1}(T - t_j) + t_{j-1}(T - t_j)}{T \tau_j \tau_{j-1}} = \frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}.
\end{aligned}$$

$$Z_j = \frac{X^{a \rightarrow b}(t_j)}{\tau_j} - \frac{X^{a \rightarrow b}(t_{j-1})}{\tau_{j-1}}$$

$$c(s, t) = s - \frac{st}{T} = \frac{s(T - t)}{T}, \quad 0 \leq s \leq t \leq T$$

$$c(t_{j-1}, t_j) = t_{j-1} - \frac{t_{j-1}t_j}{T} = \frac{t_{j-1}(T - t_j)}{T} = \frac{t_{j-1}\tau_j}{T}$$

$$\tau_j = T - t_j$$

$$\begin{aligned}
\text{Cov}(Z_i, Z_j) &= \frac{1}{\tau_i \tau_j} c(t_i, t_j) - \frac{1}{\tau_i \tau_{j-1}} c(t_i, t_{j-1}) - \frac{1}{\tau_{i-1} \tau_j} c(t_{i-1}, t_j) + \frac{1}{\tau_{i-1} \tau_{j-1}} c(t_{i-1}, t_{j-1}) \\
i < j \\
&= \frac{\cancel{t_i}(\cancel{T-t_j})}{\cancel{T\tau_i}\cancel{\tau_j}} - \frac{\cancel{t_i}(\cancel{T-t_{j-1}})}{\cancel{T\tau_i}\cancel{\tau_{j-1}}} - \frac{\cancel{t_{i-1}}(\cancel{T-t_j})}{\cancel{T\tau_{i-1}}\cancel{\tau_j}} + \frac{\cancel{t_{i-1}}(\cancel{T-t_{j-1}})}{\cancel{T\tau_{i-1}}\cancel{\tau_{j-1}}} = 0. \\
&\quad \tau_j = T - t_j
\end{aligned}$$

$$Z_j = \frac{X^{a \rightarrow b}(t_j)}{\tau_j} - \frac{X^{a \rightarrow b}(t_{j-1})}{\tau_{j-1}}$$

$$c(s, t) = s - \frac{st}{T} = \frac{s(T-t)}{T}, \quad 0 \leq s \leq t \leq T$$

$$c(t_{j-1}, t_j) = t_{j-1} - \frac{t_{j-1}t_j}{T} = \frac{t_{j-1}(T-t_j)}{T}$$

- $Z(t_1), \dots, Z(t_n)$ are jointly normal.
- $\text{Cov}(Z_i, Z_j) = 0$.

$$f_{X,Y}(x,y) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \exp \left\{ -\frac{1}{2(1-\rho^2)} \left[\frac{(x-\mu_1)^2}{\sigma_1^2} - \frac{2\rho(x-\mu_1)(y-\mu_2)}{\sigma_1\sigma_2} + \frac{(y-\mu_2)^2}{\sigma_2^2} \right] \right\}, \quad (2.2.17)$$

$\text{Cov}(X,Y)=0 \Leftrightarrow X,Y$ are independent

- The normal random variable Z_1, \dots, Z_n are independent.

- So we conclude that the normal random variable Z_1, \dots, Z_n are independent, and we can write down their joint density, which is

$$f_{Z(t_1), \dots, Z(t_n)}(z_1, \dots, z_n) = \prod_{j=1}^n \frac{1}{\sqrt{2\pi \frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}}} \exp \left\{ -\frac{1}{2} \cdot \frac{\left(z_j - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2}{\frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}} \right\}$$

$$E(Z_j) = \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}}$$

$$Var(Z_j) = \frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}$$

variance

variance

$$= \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{\left(z_j - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2}{\frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}} \right\} \cdot \prod_{j=1}^n \frac{1}{\sqrt{2\pi \frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}}}$$

接下來把z的部份做變數變換

we make the change of variables

$$z_j = \frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}}, \quad j = 1, \dots, n,$$

$$\boxed{X^{a \rightarrow b}(0) = a}$$

- Where $x_0 = a$, to find joint density for $X^{a \rightarrow b}(t_1), \dots, X^{a \rightarrow b}(t_n)$. We work first on the sum in the exponent to see the effect of this change of variables.

$$\begin{aligned}
 f_{Z(t_1), \dots, Z(t_n)}(z_1, \dots, z_n) &= \prod_{j=1}^n \frac{1}{\sqrt{2\pi \frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}}} \exp \left\{ -\frac{1}{2} \cdot \frac{\left(z_j - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2}{\frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}} \right\} \\
 &= \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{\left(z_j - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2}{\frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}} \right\} \cdot \prod_{j=1}^n \frac{1}{\sqrt{2\pi \frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}}}.
 \end{aligned}$$

- We have

$$\sum_{j=1}^n \frac{\left(z_j - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2}{\frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}} \quad \boxed{z_j = \frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}}}$$

$$= \sum_{j=1}^n \frac{\tau_j \tau_{j-1}}{t_j - t_{j-1}} \left(\frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}} - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2$$

$$= \sum_{j=1}^n \frac{\tau_j \tau_{j-1}}{t_j - t_{j-1}} \left(\frac{x_j^2}{\tau_j^2} + \frac{x_{j-1}^2}{\tau_{j-1}^2} + \frac{b^2(t_j - t_{j-1})^2}{\tau_j^2 \tau_{j-1}^2} - \frac{2x_j x_{j-1}}{\tau_j \tau_{j-1}} \right. \\ \left. - \frac{2x_j b(t_j - t_{j-1})}{\tau_j^2 \tau_{j-1}} + \frac{2x_{j-1} b(t_j - t_{j-1})}{\tau_j \tau_{j-1}^2} \right)$$

$$\boxed{(a + b + c)^2 = a^2 + b^2 + c^2 + 2ab + 2ac + 2bc}$$

$$\begin{aligned}
&= \sum_{j=1}^n \frac{\tau_j \tau_{j-1}}{t_j - t_{j-1}} \left(\frac{x_j^2}{\tau_j^2} + \frac{x_{j-1}^2}{\tau_{j-1}^2} + \frac{b^2(t_j - t_{j-1})^2}{\tau_j^2 \tau_{j-1}^2} - \frac{2x_j x_{j-1}}{\tau_j \tau_{j-1}} \right. \\
&\quad \left. - \frac{2x_j b(t_j - t_{j-1})}{\tau_j^2 \tau_{j-1}} + \frac{2x_{j-1} b(t_j - t_{j-1})}{\tau_j \tau_{j-1}^2} \right) \\
&= \sum_{j=1}^n \left(\frac{\tau_{j-1} x_j^2}{\tau_j (t_j - t_{j-1})} + \frac{\tau_j x_{j-1}^2}{\tau_{j-1} (t_j - t_{j-1})} + \frac{b^2(t_j - t_{j-1})}{\tau_j \tau_{j-1}} - \frac{2x_j x_{j-1}}{t_j - t_{j-1}} \right. \\
&\quad \left. - \frac{2x_j b}{\tau_j} + \frac{2x_{j-1} b}{\tau_{j-1}} \right)
\end{aligned}$$

$$= \sum_{j=1}^n \left(\frac{\tau_{j-1}x_j^2}{\tau_j(t_j - t_{j-1})} + \frac{\tau_j x_{j-1}^2}{\tau_{j-1}(t_j - t_{j-1})} + \frac{b^2(t_j - t_{j-1})}{\tau_j \tau_{j-1}} - \frac{2x_j x_{j-1}}{t_j - t_{j-1}} \right. \\ \left. - \frac{2x_j b}{\tau_j} + \frac{2x_{j-1} b}{\tau_{j-1}} \right)$$

$$= \sum_{j=1}^n \left[\frac{x_j^2}{t_j - t_{j-1}} \left(1 + \frac{\tau_{j-1} - \tau_j}{\tau_j} \right) + \frac{x_{j-1}^2}{t_j - t_{j-1}} \left(1 - \frac{\tau_{j-1} - \tau_j}{\tau_{j-1}} \right) \right. \\ \left. - \frac{2x_j x_{j-1}}{t_j - t_{j-1}} \right] + b^2 \sum_{j=1}^n \left(\frac{1}{\tau_j} - \frac{1}{\tau_{j-1}} \right) - 2b \sum_{j=1}^n \left(\frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}} \right).$$

$$\frac{1 + \frac{\tau_{j-1} - \tau_j}{\tau_j}}{1} = \frac{\tau_j + \tau_{j-1} - \tau_j}{\tau_j} = \frac{\tau_{j-1}}{\tau_j}$$

$$\frac{\left(\frac{1}{\tau_j} - \frac{1}{\tau_{j-1}} \right)}{1} = \frac{\tau_{j-1} - \tau_j}{\tau_j \tau_{j-1}} = \frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}$$

$$\frac{1 - \frac{\tau_{j-1} - \tau_j}{\tau_{j-1}}}{1} = \frac{\tau_{j-1} - \tau_{j-1} + \tau_j}{\tau_{j-1}} = \frac{\tau_j}{\tau_{j-1}}$$

$$\tau_{j-1} - \tau_j = (T - t_{j-1}) - (T - t_j) = t_j - t_{j-1}$$

$$\tau_{j-1} - \tau_j = (T - t_{j-1}) - (T - t_j) = t_j - t_{j-1}$$

$$\begin{aligned}
&= \sum_{j=1}^n \left[\frac{x_j^2}{t_j - t_{j-1}} \left(1 + \frac{\tau_{j-1} - \tau_j}{\tau_j} \right) + \frac{x_{j-1}^2}{t_j - t_{j-1}} \left(1 - \frac{\tau_{j-1} - \tau_j}{\tau_{j-1}} \right) \right. \\
&\quad \left. - \frac{2x_j x_{j-1}}{t_j - t_{j-1}} \right] + b^2 \sum_{j=1}^n \left(\frac{1}{\tau_j} - \frac{1}{\tau_{j-1}} \right) - 2b \sum_{j=1}^n \left(\frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}} \right) \\
&= \sum_{j=1}^n \left[\frac{x_j^2 - 2x_j x_{j-1} + x_{j-1}^2}{t_j - t_{j-1}} \right] + \sum_{j=1}^n \left(\frac{x_j^2}{\tau_j} - \frac{x_{j-1}^2}{\tau_{j-1}} \right) \\
&\quad + b^2 \sum_{j=1}^n \left(\frac{1}{\tau_j} - \frac{1}{\tau_{j-1}} \right) - 2b \sum_{j=1}^n \left(\frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}} \right)
\end{aligned}$$

$$\begin{aligned}
&= \sum_{j=1}^n \left[\frac{x_j^2 - 2x_j x_{j-1} + x_{j-1}^2}{t_j - t_{j-1}} \right] + \sum_{j=1}^n \left(\frac{x_j^2}{\tau_j} - \frac{x_{j-1}^2}{\tau_{j-1}} \right) \\
&\quad + b^2 \sum_{j=1}^n \left(\frac{1}{\tau_j} - \frac{1}{\tau_{j-1}} \right) - 2b \sum_{j=1}^n \left(\frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}} \right) \\
&= \sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}} + \frac{x_n^2}{T - t_n} - \frac{a^2}{T} + b^2 \left(\frac{1}{T - t_n} - \frac{1}{T} \right) \\
&\quad - 2b \left(\frac{x_n}{T - t_n} - \frac{a}{T} \right)
\end{aligned}$$

$$\boxed{\tau_j = T - t_j} \quad \boxed{x_0 = a}$$

$$\sum_{j=1}^n \left(\frac{x_j^2}{\tau_j} - \frac{x_{j-1}^2}{\tau_{j-1}} \right) = \left(\frac{x_1^2}{\tau_1} - \frac{x_0^2}{\tau_0} \right) + \left(\frac{x_2^2}{\tau_2} - \frac{x_1^2}{\tau_1} \right) + \dots + \left(\frac{x_n^2}{\tau_n} - \frac{x_{n-1}^2}{\tau_{n-1}} \right) = \left(\frac{x_n^2}{\tau_n} - \frac{x_0^2}{\tau_0} \right)$$

$$\sum_{j=1}^n \left(\frac{1}{\tau_j} - \frac{1}{\tau_{j-1}} \right) = \left(\frac{1}{\tau_1} - \frac{1}{\tau_0} \right) + \left(\frac{1}{\tau_2} - \frac{1}{\tau_1} \right) + \dots + \left(\frac{1}{\tau_n} - \frac{1}{\tau_{n-1}} \right) = \left(\frac{1}{\tau_n} - \frac{1}{\tau_0} \right)$$

$$\sum_{j=1}^n \left(\frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}} \right) = \left(\frac{x_1}{\tau_1} - \frac{x_0}{\tau_0} \right) + \left(\frac{x_2}{\tau_2} - \frac{x_1}{\tau_1} \right) + \dots + \left(\frac{x_n}{\tau_n} - \frac{x_{n-1}}{\tau_{n-1}} \right) = \left(\frac{x_n}{\tau_n} - \frac{x_0}{\tau_0} \right)$$

$$\begin{aligned}
&= \underbrace{\sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}}}_{\text{blue}} + \underbrace{\frac{x_n^2}{T - t_n} - \frac{a^2}{T}}_{\text{purple}} + \underbrace{b^2 \left(\frac{1}{T - t_n} - \frac{1}{T} \right)}_{\text{orange}} \\
&\quad - \underbrace{2b \left(\frac{x_n}{T - t_n} - \frac{a}{T} \right)}_{\text{purple}} \\
&= \underbrace{\sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}}}_{\text{blue}} + \underbrace{\frac{(b - x_n)^2}{T - t_n}}_{\text{purple}} - \underbrace{\frac{(b - a)^2}{T}}_{\text{orange}}.
\end{aligned}$$

$$\begin{aligned}
&\exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{\left(z_j - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2}{\frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}} \right\} \\
&= \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}} - \frac{(b - x_n)^2}{2(T - t_n)} + \frac{(b - a)^2}{2T} \right\}.
\end{aligned}$$

- To change a density, we also need to account for the Jacobian of the change of variables. In this case, we have

$$\frac{\partial z_j}{\partial x_j} = \frac{1}{\tau_j}, \quad j = 1, \dots, n,$$

$$\frac{\partial z_j}{\partial x_{j-1}} = -\frac{1}{\tau_{j-1}}, \quad j = 2, \dots, n,$$

$$z_j = \frac{x_j}{\tau_j} - \frac{x_{j-1}}{\tau_{j-1}}$$

and all other partial derivatives are zero. This leads to the Jacobian matrix

$$J = \begin{bmatrix} \frac{1}{\tau_1} & 0 & \dots & 0 \\ -\frac{1}{\tau_1} & \frac{1}{\tau_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \frac{1}{\tau_n} \end{bmatrix}$$

- Whose determinant is $\prod_{j=1}^n \frac{1}{\tau_j}$. Multiplying $f_{Z(t_1), \dots, Z(t_n)}(z_1, \dots, z_n)$ by this determinant and using the change of variables worked out above, we obtain the density for $X^{a \rightarrow b}(t_1), \dots, X^{a \rightarrow b}(t_n)$,

$$J = \begin{bmatrix} \frac{1}{\tau_1} & 0 & \dots & 0 \\ \frac{1}{\tau_1} & \frac{1}{\tau_2} & \dots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \dots & \frac{1}{\tau_n} \end{bmatrix}$$

$$f_{X^{a \rightarrow b}(t_1), \dots, X^{a \rightarrow b}(t_n)}(x_1, \dots, x_n)$$

$$= \prod_{j=1}^n \frac{1}{\sqrt{2\pi(t_j - t_{j-1})}} \sqrt{\frac{\tau_{j-1}}{\tau_j}}$$

$$\cdot \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}} - \frac{(b - x_n)^2}{2(T - t_n)} + \frac{(b - a)^2}{2T} \right\}$$

determinant is $\prod_{j=1}^n \frac{1}{\tau_j}$

$$f_{Z(t_1), \dots, Z(t_n)}(z_1, \dots, z_n) = \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{\left(z_j - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2}{\frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}} \right\} \cdot \prod_{j=1}^n \frac{1}{\sqrt{2\pi \frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}}}$$

$$\exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{\left(z_j - \frac{b(t_j - t_{j-1})}{\tau_j \tau_{j-1}} \right)^2}{\frac{t_j - t_{j-1}}{\tau_j \tau_{j-1}}} \right\}$$

$$= \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}} - \frac{(b - x_n)^2}{2(T - t_n)} + \frac{(b - a)^2}{2T} \right\}$$

$$\begin{aligned}
&= \prod_{j=1}^n \frac{1}{\sqrt{2\pi(t_j - t_{j-1})}} \sqrt{\frac{\tau_{j-1}}{\tau_j}} \\
&\quad \cdot \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}} - \frac{(b - x_n)^2}{2(T - t_n)} + \frac{(b - a)^2}{2T} \right\} \\
&= \sqrt{\frac{T}{T - t_n}} \cdot \prod_{j=1}^n \frac{1}{\sqrt{2\pi(t_j - t_{j-1})}} \\
&\quad \cdot \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}} - \frac{(b - x_n)^2}{2(T - t_n)} + \frac{(b - a)^2}{2T} \right\}
\end{aligned}$$

$$\prod_{j=1}^n \sqrt{\frac{\tau_{j-1}}{\tau_j}} = \sqrt{\frac{\tau_0}{\tau_1}} \times \cancel{\sqrt{\frac{\tau_1}{\tau_2}}} \times \dots \times \cancel{\sqrt{\frac{\tau_{n-1}}{\tau_n}}} = \sqrt{\frac{\tau_0}{\tau_n}}$$

$$\begin{aligned}
&= \sqrt{\frac{T}{T-t_n}} \cdot \prod_{j=1}^n \frac{1}{\sqrt{2\pi(t_j - t_{j-1})}} \boxed{\times \frac{\sqrt{2\pi}}{\sqrt{2\pi}}} \\
&\quad \cdot \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \frac{(x_j - x_{j-1})^2}{t_j - t_{j-1}} - \frac{(b - x_n)^2}{2(T - t_n)} + \frac{(b - a)^2}{2T} \right\} \\
&= \frac{p(T - t_n, x_n, b)}{p(T, a, b)} \prod_{j=1}^n p(t_j - t_{j-1}, x_{j-1}, x_j), \tag{4.7.6}
\end{aligned}$$

where

$$p(\tau, x, y) = \frac{1}{\sqrt{2\pi\tau}} \exp \left\{ -\frac{(y - x)^2}{2\tau} \right\}$$

is the transition density for Brownian motion. 課本p.108

4.7.5 Brownian Bridge as a Conditioned Brownian Motion

- The joint density (4.7.6) for $X^{a \rightarrow b}(t_1), \dots, X^{a \rightarrow b}(t_n)$ permits us to give one more interpretation for Brownian bridge from a to b on $[0, T]$. It is a Brownian motion $W(t)$ on this time interval, starting at $W(0) = a$ and conditioned to arrive at b at time T (i.e., conditioned on $W(T) = b$). Let $0 = t_0 < t_1 < t_2 < \dots < t_n < T$ be given. The joint density of $W(t_1), \dots, W(t_n), W(T)$ is

$$f_{W(t_1), \dots, W(t_n), W(T)}(x_1, \dots, x_n, b) = \underbrace{p(T - t_n, x_n, b) \prod_{j=1}^n p(t_j - t_{j-1}, x_{j-1}, x_j)}_{\text{where } W(0) = x_0 = a} \quad (4.7.7)$$

This is because $p(t_1 - t_0, x_0, x_1) = p(t_1, a, x_1)$ is the density for the Brownian motion going from $W(0) = a$ to $W(t_1) = x_1$ in the time between $t = 0$ and $t = t_1$. Similarly, $p(t_2 - t_1, x_1, x_2)$ is the density for going from $W(t_1) = x_1$ to $W(t_2) = x_2$ between time $t = t_1$ and $t = t_2$. The joint density for $W(t_1)$ and $W(t_2)$ is then the product

$$\underline{p(t_1, a, x_1) p(t_2 - t_1, x_1, x_2)}.$$

Continuing in this way, we obtain the joint density (4.7.7).

The marginal density of $W(T)$ is $p(T, a, b)$.

So, the density of $W(t_1), \dots, W(t_n)$ conditioned on $W(T) = b$ is thus the quotient

$$\frac{p(T - t_n, x_n, b)}{p(T, a, b)} \prod_{j=1}^n p(t_j - t_{j-1}, x_{j-1}, x_j)$$

joint density of
 $W(t_1), \dots, W(t_n),$
 $W(T)$

marginal density of $W(T)$

and this is $f_{X^{a \rightarrow b}(t_1), \dots, X^{a \rightarrow b}(t_n)}(x_1, \dots, x_n)$ of (4.7.6).

Finally, let us define

$$M^{a \rightarrow b}(T) = \max_{0 \leq t \leq T} X^{a \rightarrow b}(t)$$

to be the maximum value obtained by the Brownian bridge from a to b on $[0, T]$. This random variable has the following distribution.

Corollary 4.7.7.

The density of $M^{a \rightarrow b}(T)$ is

Brownian bridge from a to b on $[0, T] \rightarrow$ a Brownian motion $W(t)$ on this time interval, starting at $W(0) = a$ and conditioned on $W(T) = b$

$$f_{M^{a \rightarrow b}(T)}(y) = \frac{2(2y - b - a)}{T} e^{-\frac{2}{T}(y-a)(y-b)}, \quad y > \max\{a, b\}. \quad (4.7.8)$$

Proof: Because the Brownian bridge from 0 to w on $[0, T]$ is a Brownian motion conditioned on $W(T) = w$, the maximum of $X^{0 \rightarrow w}$ on $[0, T]$ is the maximum of W on $[0, T]$ conditioned on $W(T) = w$. Therefore, the density of $M^{0 \rightarrow w}(T)$ was computed in Corollary 3.7.4 and is

$$f_{M^{0 \rightarrow w}(T)}(m) = \frac{2(2m - w)}{T} e^{-\frac{2m(m-w)}{T}}, \quad w < m, m > 0. \quad (4.7.9)$$

Corollary 3.7.4. *The conditional distribution of $M(t)$ given $W(t) = w$ is the maximum of the Brownian motion on $[0, t]$*

$$f_{M(t)|W(t)}(m|w) = \frac{2(2m - w)}{t} e^{-\frac{2m(m-w)}{t}}, \quad w \leq m, m > 0.$$

Corollary 4.7.7.

The density of $M^{a \rightarrow b}(T)$ is

$$f_{M^{a \rightarrow b}(T)}(y) = \frac{2(2y - b - a)}{T} e^{-\frac{2}{T}(y-a)(y-b)}, \quad y > \max\{a, b\}. \quad (4.7.8)$$

Proof : Because the Brownian bridge from 0 to w on $[0, T]$ is a Brownian motion conditioned on $W(T) = w$, the maximum of $X^{0 \rightarrow w}$ on $[0, T]$ is the maximum of W on $[0, T]$ conditioned on $W(T) = w$. Therefore, the density of $M^{0 \rightarrow w}(T)$ was computed in Corollary 3.7.4 and is

$$f_{M^{0 \rightarrow w}(T)}(m) = \frac{2(2m - w)}{T} e^{-\frac{2m(m-w)}{T}}, \quad w < m, \quad m > 0. \quad (4.7.9)$$

The density of $f_{M^{a \rightarrow b}(T)}(y)$ can be obtained by translating from the initial condition $W(0) = a$ to $W(0) = 0$ and using (4.7.9). In particular, in (4.7.9) we replace m by $y - a$ and replace w by $b - a$. This result in (4.7.8).